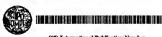
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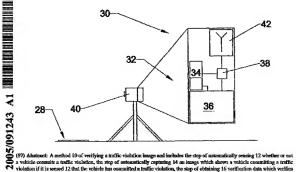
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violation if it is sensed 12 that the vehicle has committed a traffic violation, the step of obtaining 15 verification data which verifies that the step of sensing 12 is accurate within acceptable limits, and the step of automatically combining 18 the obtained verification data with the captured traffic violation image to provide proof of the accurate sensing of the traffic violation. Also provided is an associated system.